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****** APPENDIX B
                         **********
                           Noise Cancelling
/* Example for constant saturation approach to noise cancelling */
#define LAMBDA 0.95
void OxiLSL NC( int
                       reset,
                       passes,
               int
                       sat_factor,
               int
                       *signal_1,
*signal_2,
*target_1,
*target_2) {
               int
               int
               int
               int
               i, ii, k, m, n, contraction;
       int
               *s_a, *s_b, *out_a, *out_b;
static int
               Delta_sqr, scale, noise_ref;
static float
if ( reset == TRUE) {
        = signal_1;
  s a
  sb = signal 2;
  out a = target 1;
  out b = target 2;
  scale = 1.0 /4160.0;
/* noise canceller initialization at time t=0 */
  nc[0].berr = 0.0;
  nc[0].Gamma = 1.0;
  for (m=0; m<NC CELLS; m++) {
    nc(m).err_a
                = 0.0;
    nc(m).err_b
                  = 0.0;
    nc[m].Roh_a
                  = 0.0;
    nc[m].Roh b
                  = 0.0;
    nc(m).Delta
                  = 0.0;
    nc(m).Fswsqr = 0.00001;
    nc[m].Bswsqr = 0.00001;
  }
 }
/*======= END INITIALIZATION =======
 for(k=0; k<passes; k++){</pre>
   contraction = FALSE;
  for(m=0; m< NC_CELLS; m++) {
  nc[m].berr1 = nc[m].berr;</pre>
                                       /* Update delay elements
    nc(m).Bswsqr1 = nc(m).Bswsqr;
              = sat_factor * log(1.0 - (*s_a) * scale)
   noise_ref
              -\log(1.0 - (*s_b) * scale);
   nc[0].err_a = log(1.0 - (*s_a) * scale);
   nc[0].err_b = log(1.0 - (*s_b) * scale);
   ++s_a;
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```
++s b;
nc[0].ferr
            = noise ref ;
nc(0).berr
            = noise ref ;
nc[0].Fswsqr = LAMBDA * nc[0].Fswsqr + noise_ref * noise_ref;
nc[0].Bswsqr = nc[0].Fswsqr;
/* Order Update
for(n=1; ( n < NC_CELLS) && (contraction == FALSE); n++) {
 /* Adaptive Lattice Section */
 m = n-1;
 ii=n-1;
 nc(m).Delta *=
                 LAMBDA;
 nc(m).Delta +=
                 nc(m).berr1 * nc(m).ferr / nc(m).Gamma ;
 Delta sqr
                 nc(m).Delta * nc(m).Delta;
              = -nc(m).Delta / nc(m).Bswsqr1;
 nc[n].fref
              = -nc(m).Delta / nc(m).Fswsqr;
 nc(n).bref
 nc(n).ferr
              = nc(m).ferr + nc(n).fref * nc(m).berr1;
 nc(n).berr
                nc(m).berr1 + nc(n).bref * nc(m).ferr;
              =
 nc(n).Fswsqr = nc(m).Fswsqr - Delta_sqr / nc(m).Bswsqr1;
 nc(n).Bswsqr = nc(m).Bswsqr1 - Delta_sqr / nc(m).Fswsqr;
 if( (nc[n].Fswsqr + nc[n].Bswsqr) > 0.00001 || (n < 5) ) {
   nc[n].Gamma = nc[m].Gamma - nc[m].berr1 * nc[m].berr1 / nc[m].Bswsqr1;
   if(nc[n].Gamma < 0.05) nc[n].Gamma = 0.05;
   if(nc[n].Gamma > 1.00) nc[n].Gamma = 1.00;
 /* Joint Process Estimation Section */
   nc[m].Roh a *= LAMBDA;
   nc(m).Roh_a += nc(m).berr * nc(m).err_a / nc(m).Gamma;
              = nc[m].Roh_a / nc[m].Bswsqr;
   nc(m).k_a
   nc(n).err_a = nc(m).err_a - nc(m).k a * nc(m).berr;
  nc[m].Roh b \neq LAMBDA:
  nc[m].Roh_b += nc[m].berr * nc[m].err_b / nc[m].Gamma;
              = nc(m).Roh_b / nc(m).Bswsqr;
  nc(m).k b
  nc(n).err_b = nc(m).err_b - nc(m).k_b * nc(m).berr;
}
else {
  contraction = TRUE;
  for(i=n; i<NC_CELLS; i++) {</pre>
    nc[i].err_a
                  = 0.0;
    nc[i].Roh_a
                  = 0.0;
                  = 0.0;
    nc[i].err_b
    nc(i).Roh_b
                  = 0.0;
    nc[i].Delta
                  = 0.0;
    nc(i).Fswsqr
                  = 0.00001;
    nc(i).Bswsgr
                  = 0.00001;
    nc(i).Bswsqr1 = 0.00001;
```